

# Multiprime Strategies for Serial Evaluations of eSIDH-Like Isogenies

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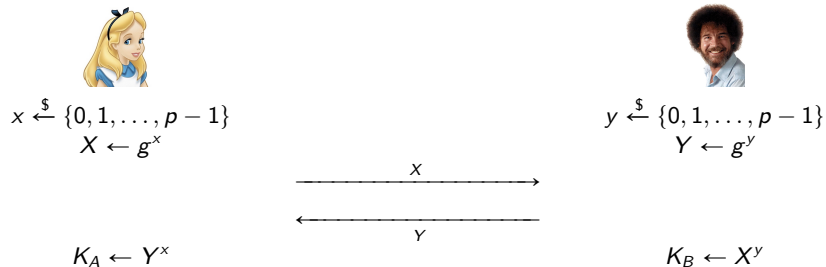


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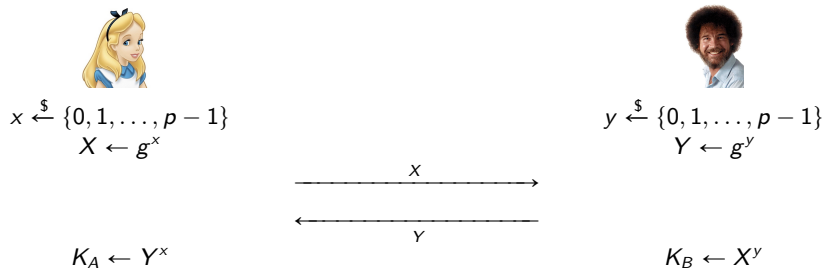
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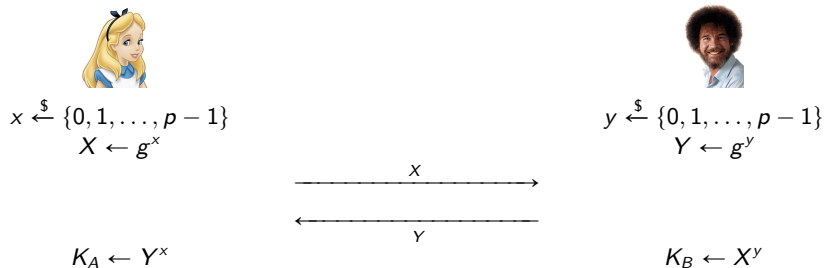
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**Security:** In the quantum setting, **completely broken** by Shor's algorithm. We need new primitives.

# Elliptic Curves

For my purposes, an **elliptic curve** is a set of the form

$$E_C/k = \{(x, y) \in \bar{k}^2 : y^2 = x^3 + Cx^2 + x\} \sqcup \{\infty\}$$

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I will also care about the  $k$ -rational points of a curve:

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# Elliptic Curves and the Group Law

Here's (the real points of) an elliptic curve:

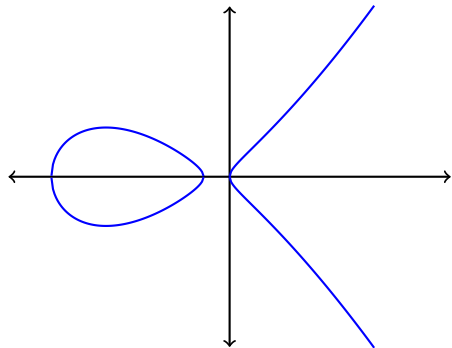


Figure: The curve  $E_3/\mathbb{R} : y^2 = x^3 + 3x^2 + x$ .



# Elliptic Curves and the Group Law

Every elliptic curve is also a group, using the chord and tangent law.

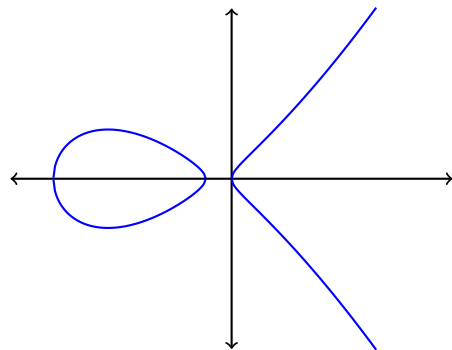


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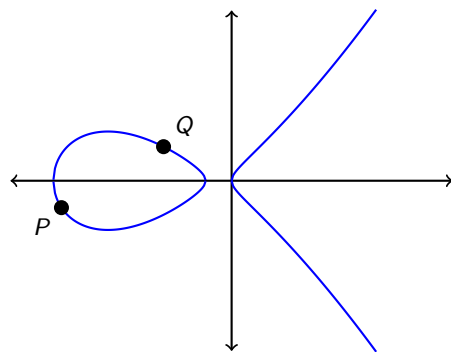


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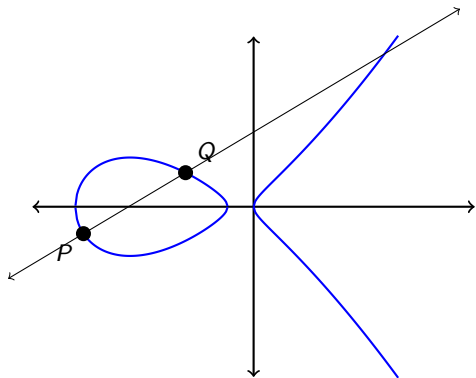


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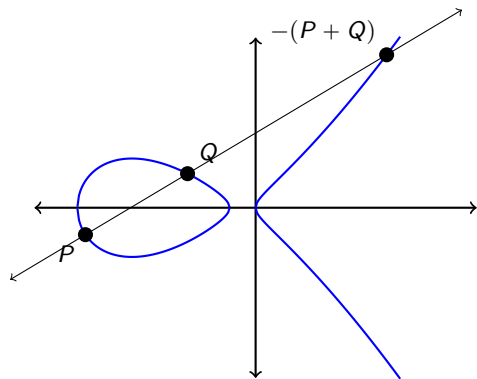


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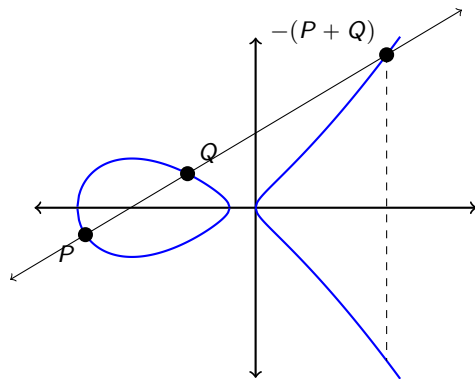


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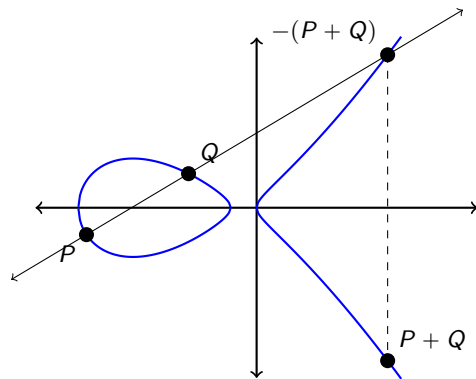


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With this group operation in mind, I define the  $m$ -**torsion subgroup** of an elliptic curve as

$$E[m] = \{P \in E : [m]P = \infty\}.$$

(here  $[m]$  is the multiplication-by- $m$  map).

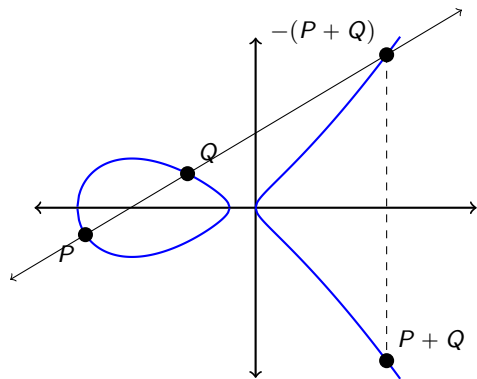


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In classical cryptography, supersingular elliptic curves are not used as platform groups for Diffie-Hellman, since the discrete logarithm problem can be solved on such curves in subexponential time.

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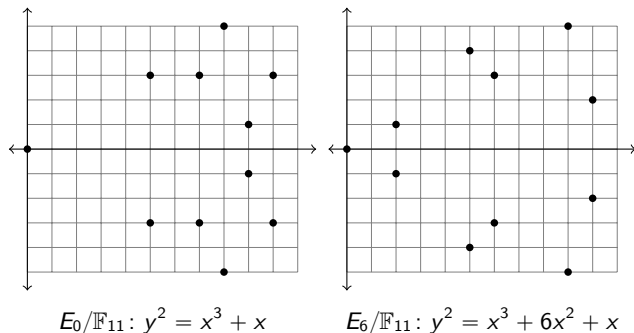
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## Example: An Isogeny

These curves are related by the isogeny

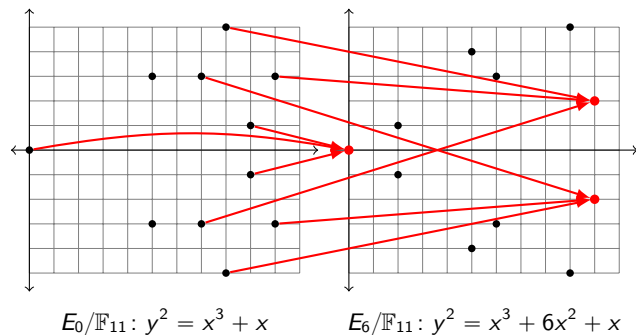
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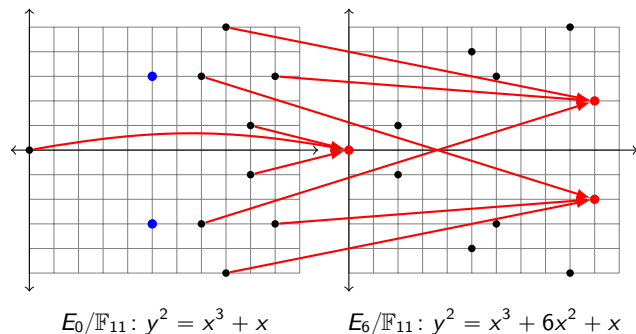
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We have  $\deg \psi = 3$ , so as you expect it is a 3-to-1 map. Its kernel is

$$\ker \psi = \{\infty, (5, 3), (5, 8)\} = \langle (5, 3) \rangle.$$



# SIDH: Protocol Description

## Global parameters:

- A prime  $p = \ell_A^{e_A} \ell_B^{e_B} - 1$  for small primes  $\ell_A \neq \ell_B$ ;
- A supersingular elliptic curve  $E/\mathbb{F}_{p^2}$  with  $|E(\mathbb{F}_{p^2})| = (p + 1)^2$ ; and,
- Torsion bases  $\{P_A, Q_A\} \subseteq E(\mathbb{F}_{p^2})$  for  $E[\ell_A^{e_A}]$ ,  $\{P_B, Q_B\} \subseteq E(\mathbb{F}_{p^2})$  for  $E[\ell_B^{e_B}]$ .

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This only works because  $E$  is supersingular and because of the special form of  $p$ .

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Running SIDH quickly  $\iff$  finding the  $Q_{A,i}$  quickly.

## A Common Thread: Strategies

- There is an obvious way for Alice to compute her  $Q_{A,i}$ :
  - Set  $R_A = P_A + xQ_A$
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  - Vertices  $\iff$  Points on curves
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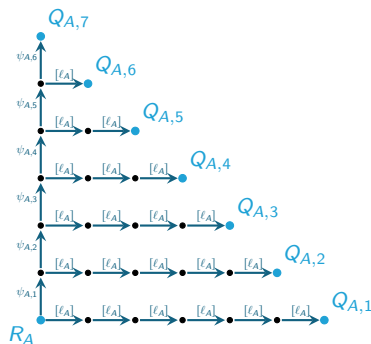


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- There are some “unused edges”:

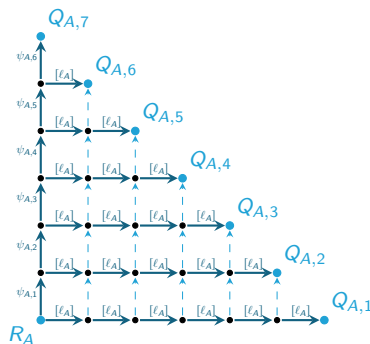


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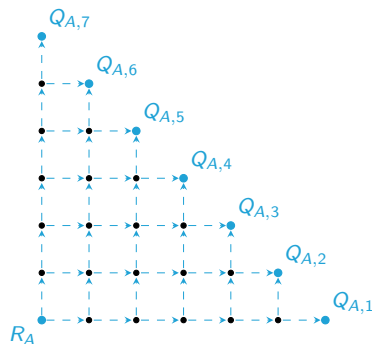


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(A Steiner arborescence in  $G$  with root  $r$  and terminals  $T$  is a connected subgraph of  $G$  that contains a path from  $r$  to each element of  $T$ , and has no undirected cycles).

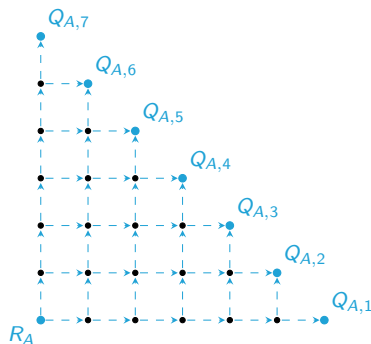


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- We call such an arborescence a **strategy**. Here's one:

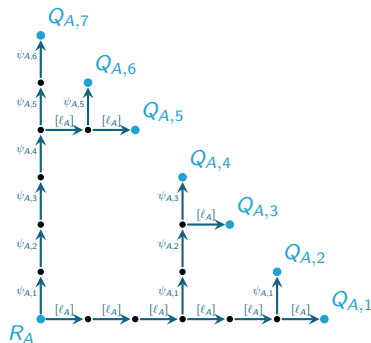


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For SIKEp434 (*i.e.*, for the prime  $p = 2^{216}3^{137} - 1$ ):

- Multiplication by 3 takes 2965 cycles/11 field multiplications
- 3-isogeny evaluation takes 1478 cycles/5.6 field multiplications

# Strategies in Weighted Graphs for SIDH

We can redraw the graph so that it better depicts the algorithm's cost; in this drawing, the total length of solid edges is (a proxy for) running time:

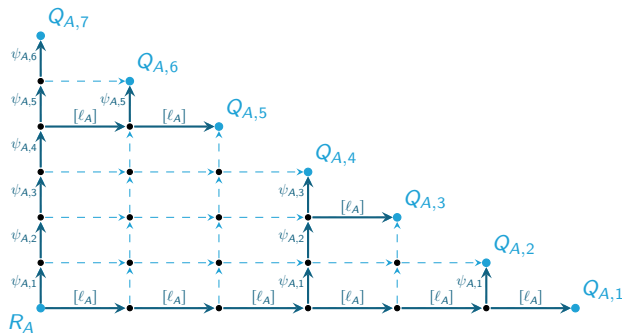


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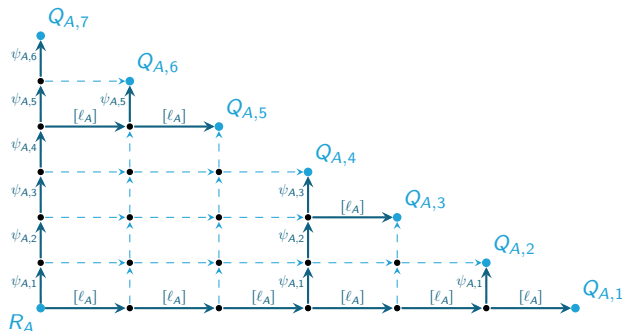


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## Strategies in Weighted Graphs for SIDH

We can redraw the graph so that it better depicts the algorithm's cost; in this drawing, the total length of solid edges is (a proxy for) running time:

For the cost model (11,5.6) from before, this strategy is optimal.

De Feo–Jao–Plût (2011) construct optimal strategies for SIDH using a recursive decomposition/dynamic programming technique.

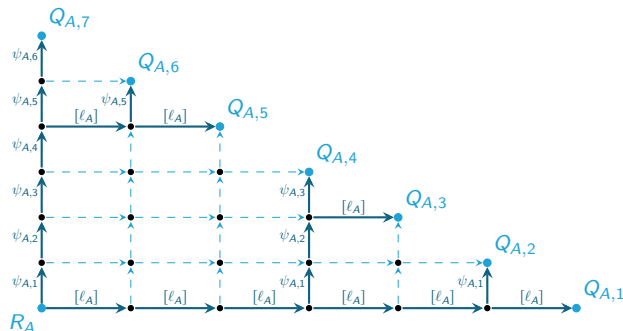


Figure: A weighted strategy for  $\ell_A = 3$  and  $e_A = 7$ .

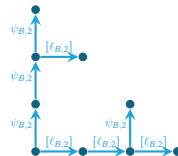
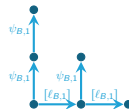
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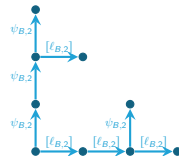
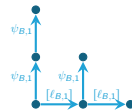


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But each “small” strategy requires a torsion basis to construct the root... So in the *second* round, these must be constructed using costly scalar multiplications.



## Multiprime Strategies in Serial eSIDH

Note that if  $E[\ell_{B,1}^{eB,1}] = \langle P_1, Q_1 \rangle$  and  $E[\ell_{B,2}^{eB,2}] = \langle P_2, Q_2 \rangle$  then for any  $\beta_1, \beta_2$  there exists an integer  $\beta^*$  such that

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I don't just need to optimize the strategy, but the **permutation** too.



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The reality: for fixed  $\vec{\ell}$ ,

- Given  $\Sigma$ , we can find the optimal  $S$  (dynamic programming *à la* De Feo-Jao-Plût);
- Given  $S$ , we can find the optimal  $\Sigma$  (linear programming);
- Stochastic search yields  $(\Sigma, S)$  which improves upon the state-of-the-art.

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We can drop  $\Sigma \in \mathbb{Z}^{n \times n}$  because the feasible polytope is integral. Then solve an LP for  $\Sigma$ .

## eSIDH Timing Estimates

Scheme	Operation	Timings (Mcycles)		Improvement
		Split Prime	Multiprime	
$p_{443} = 2^{222}3^{73}5^{45} - 1$				
eSIDH	Bob R1	7.44	7.75	-4.03%
	<b>Bob R2</b>	<b>7.00</b>	<b>6.47</b>	<b>8.24%</b>
eSIKE	Keygen	7.43	7.74	-4.01%
	<b>Decap</b>	<b>13.71</b>	<b>13.17</b>	<b>4.10%</b>
$p_{765} = 2^{391}3^{119}5^{81} - 1$				
eSIDH	Bob R1	27.14	28.37	-4.34%
	<b>Bob R2</b>	<b>25.56</b>	<b>23.90</b>	<b>6.96%</b>
eSIKE	Keygen	27.14	28.39	-4.42%
	<b>Decap</b>	<b>50.47</b>	<b>48.83</b>	<b>3.36%</b>

Table: eSIDH/eSIKE timing results on Intel i7-8650u processor.